



RFID

JOURNAL

VIRTUALLY

LIVE!

SEPTEMBER 30 - OCTOBER 1, 2020

Use of Drones for Outdoor Inventory

The cases of Metal Pipes and Cattle

Tali Freed, Ph.D., P.E.

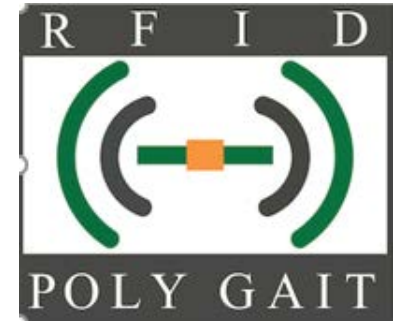
Professor of Industrial & Manufacturing Engineering

Director – The Cal Poly Center for Global Automatic Inference Technologies

California Polytechnic State University, San Luis Obispo, CA USA

With Colleague: Dr. Mason Medizade, Mechanical Engineering

& Students: Neil Wolfe, Allen Duong, Maxime Jeanneau, Tori Carson



Use of UAV-RFID for Oilfield Tubulars

Hundreds or thousands tubulars



Across large fields

Labor Intensive Inventory



RFID to the Rescue

Passive UHF RFID

Tag cost = \$0.15

Adhered to pipe cap
or to foam insulator

RFID reader on UAV



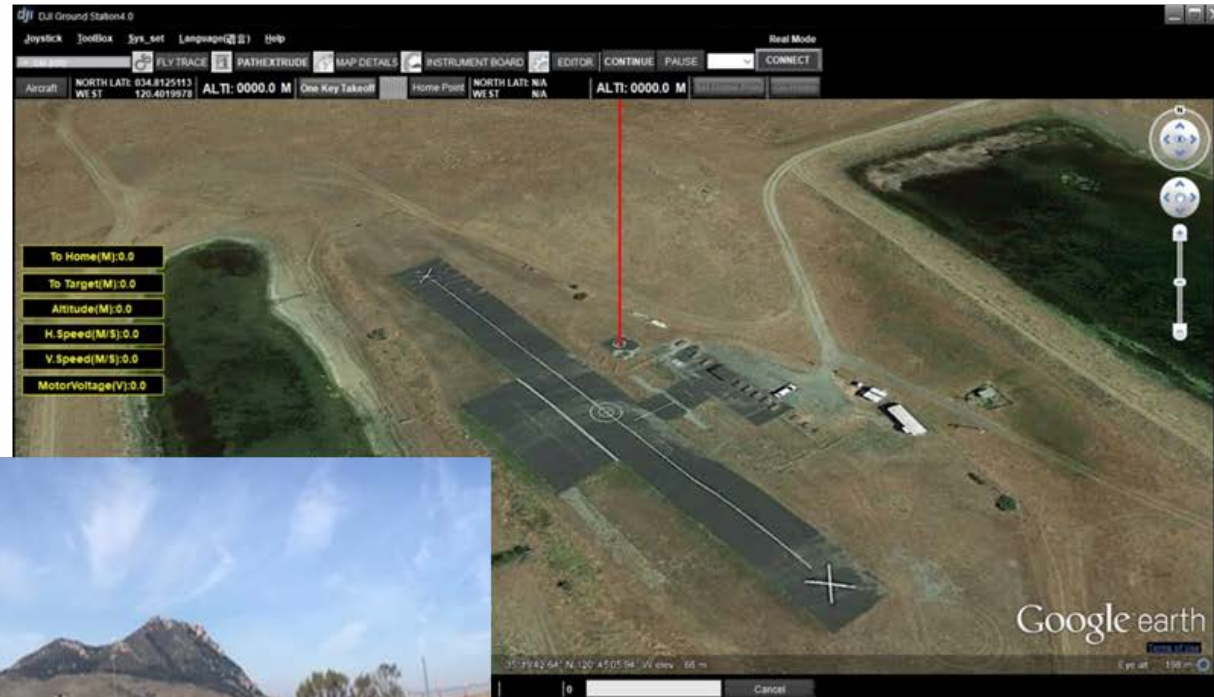
Experiment #1 – Establish Base Read Range

Experimental Flight Range

Read range testing

Zip ties for tag attachment

Promising results – 12'



Experiment #2 – Reading Reliability on Oilfield Tubulars

Santa Maria Holdings Site

Oil drilling pipes

Tags on insulation strips

Results: 3m 100% read 2
minute hover time



Experiment #3 – Reading 2 Tag Types

Cal Poly Experimental Site

Insulated hot water pipes

Insulated tags on metal
Labels on pipe insulation

Results: 2.5m 95% read
2 minute hover time



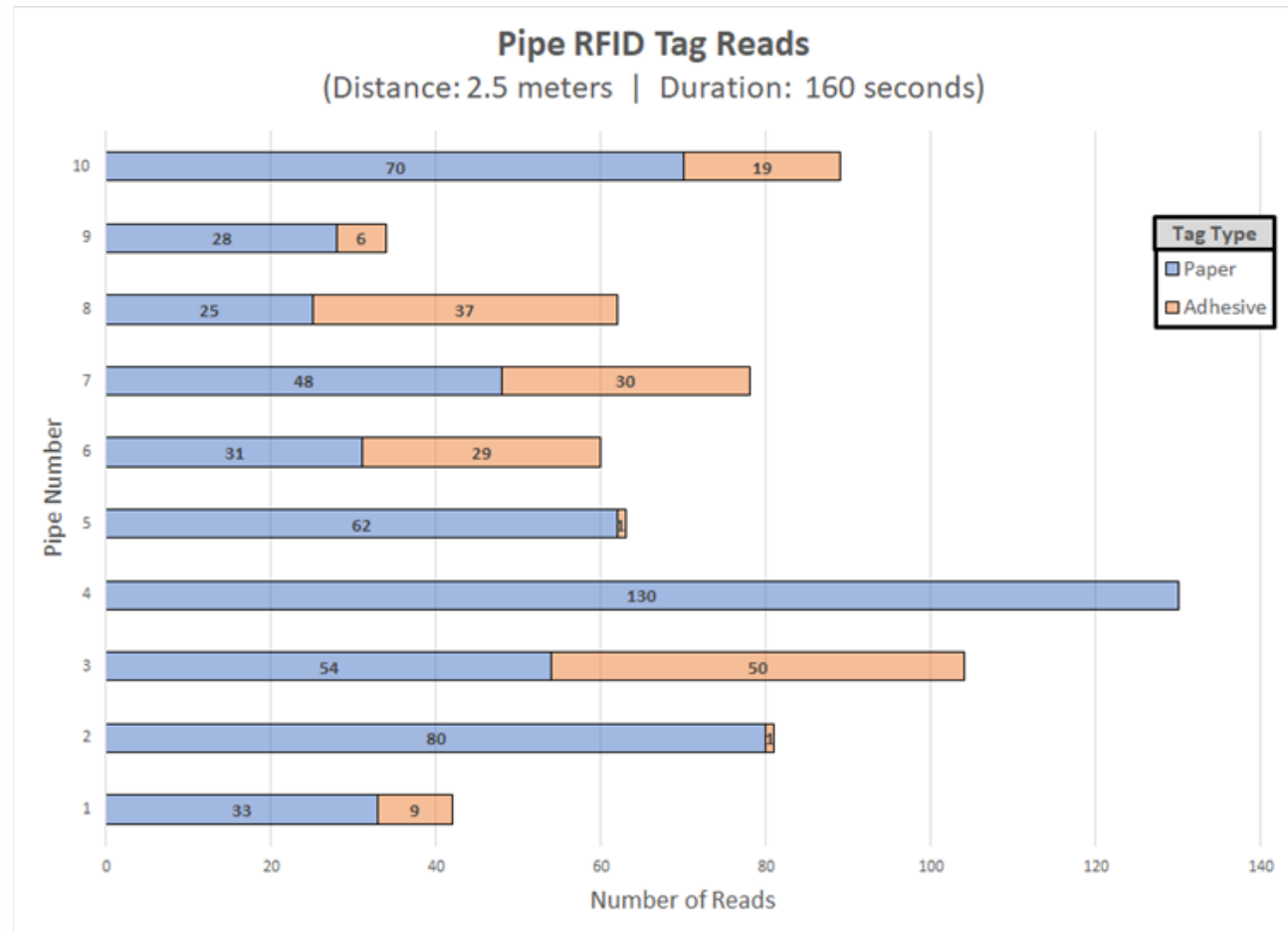
Number of Tag Reads – Reading Reliability

Variability is common

Experiment with tag types

Experiment with insulation

Results: 2.5m 95% read
with adhesive,
100% read of paper tags



Conclusions and Future Research

Variability is common

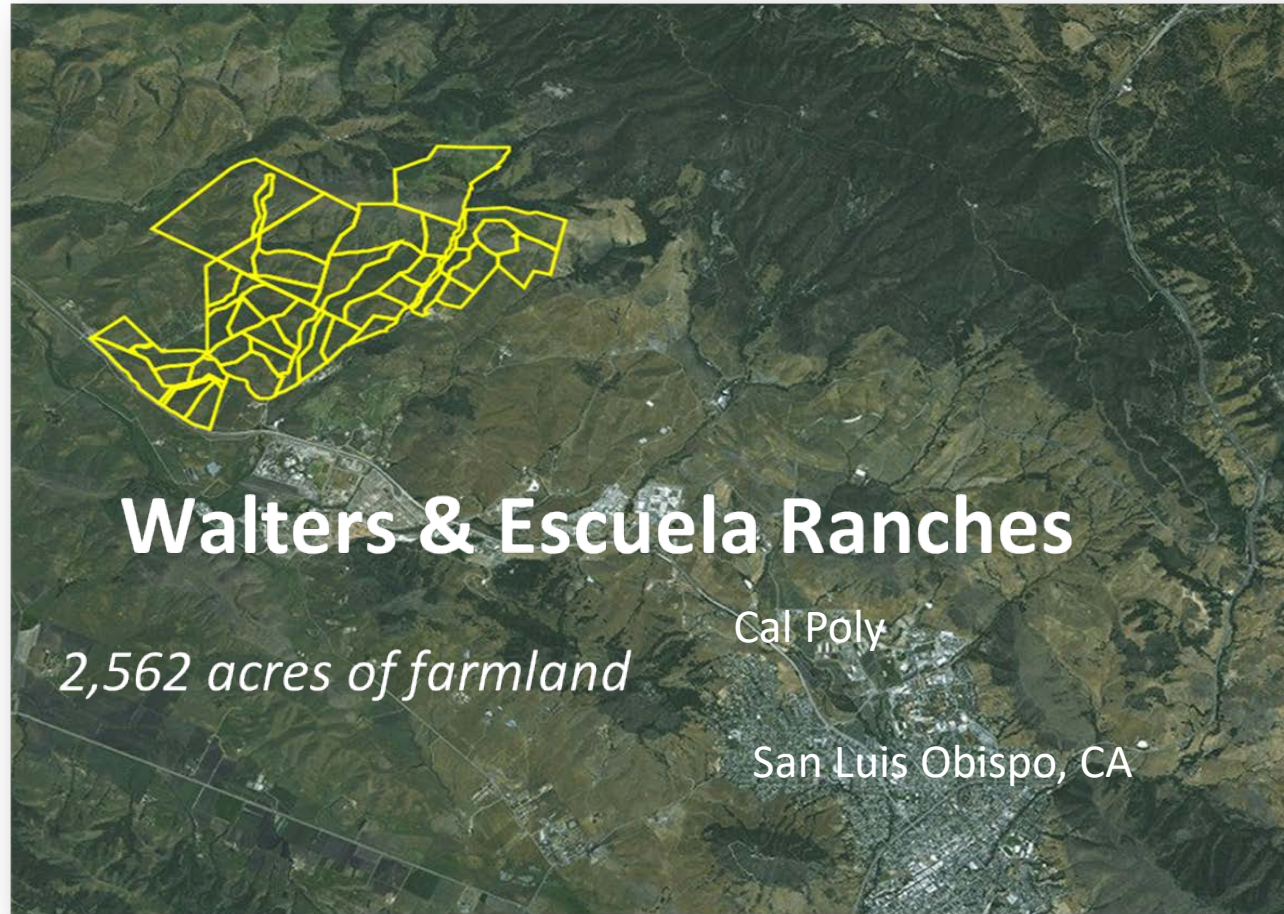
Experiment with tag types

Experiment with insulation

Results: Promising, require more experimentation: layouts, materials, environmental conditions



Use of UAV-RFID for Grazing Cattle Inventory



Livestock Tracking



UAV-RFID *System Constraints*

RFID scanning radius

350 ft \approx 106m

UAV Flight Speed

16 m/s

Ranch Area

2,562 acres

RFID scanning area

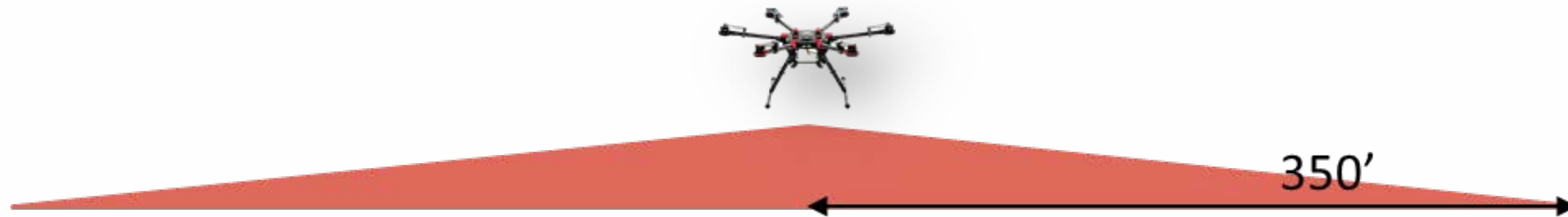
35753 m²

UAV Flight Time per Charge

15 min

Intensive Grazing Pasture Area

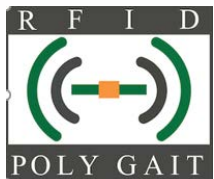
up to 293 acres



Problem

To utilize the RFID-UAV system for cattle tracking, the following must be considered:

- *The location of each cow is unknown within the pasture.*
- *The UAV must fly within 350' of each cow.*
- *The UAV flight time is limited to 15 minutes.*

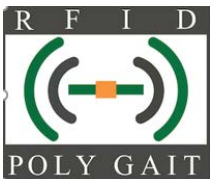


SEPTEMBER 30 - OCTOBER 1, 2020

Alternatives Considered

System Adjustments

- Increase the flight time
- Enhance read range
- Additional UAV + RFID interrogator
- Reduce the flight path



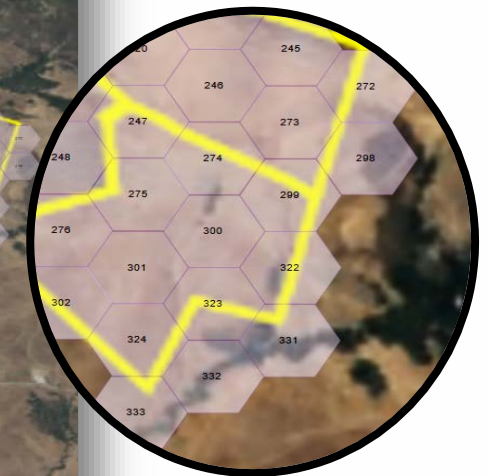
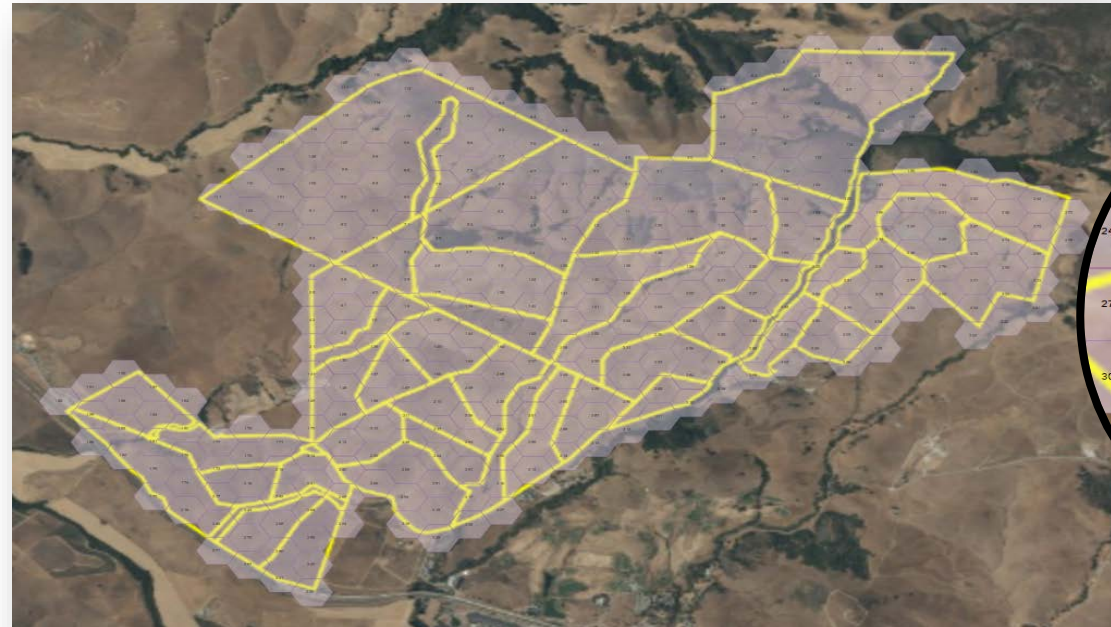
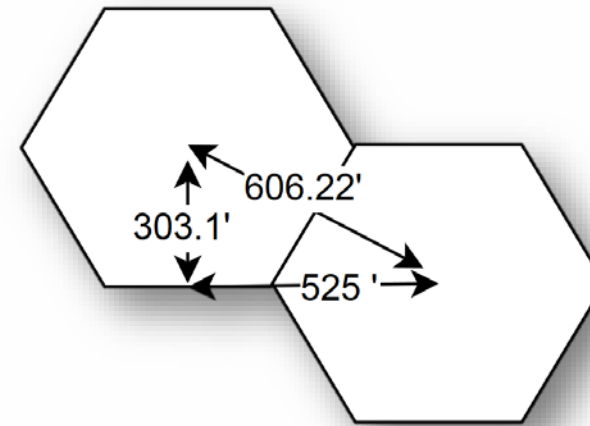
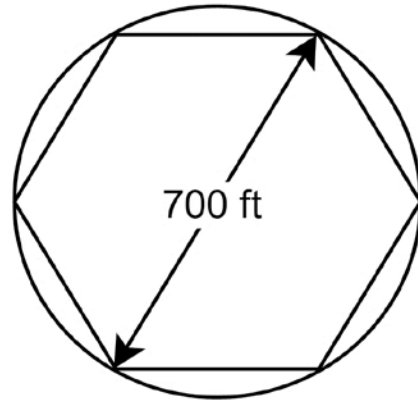
SEPTEMBER 30 - OCTOBER 1, 2020

Path Optimization Method – *Traveling Salesman Problem*

1. Identify Nodes
2. Heuristic Approach to Minimize Number of Nodes
3. Traditional TSP Solution

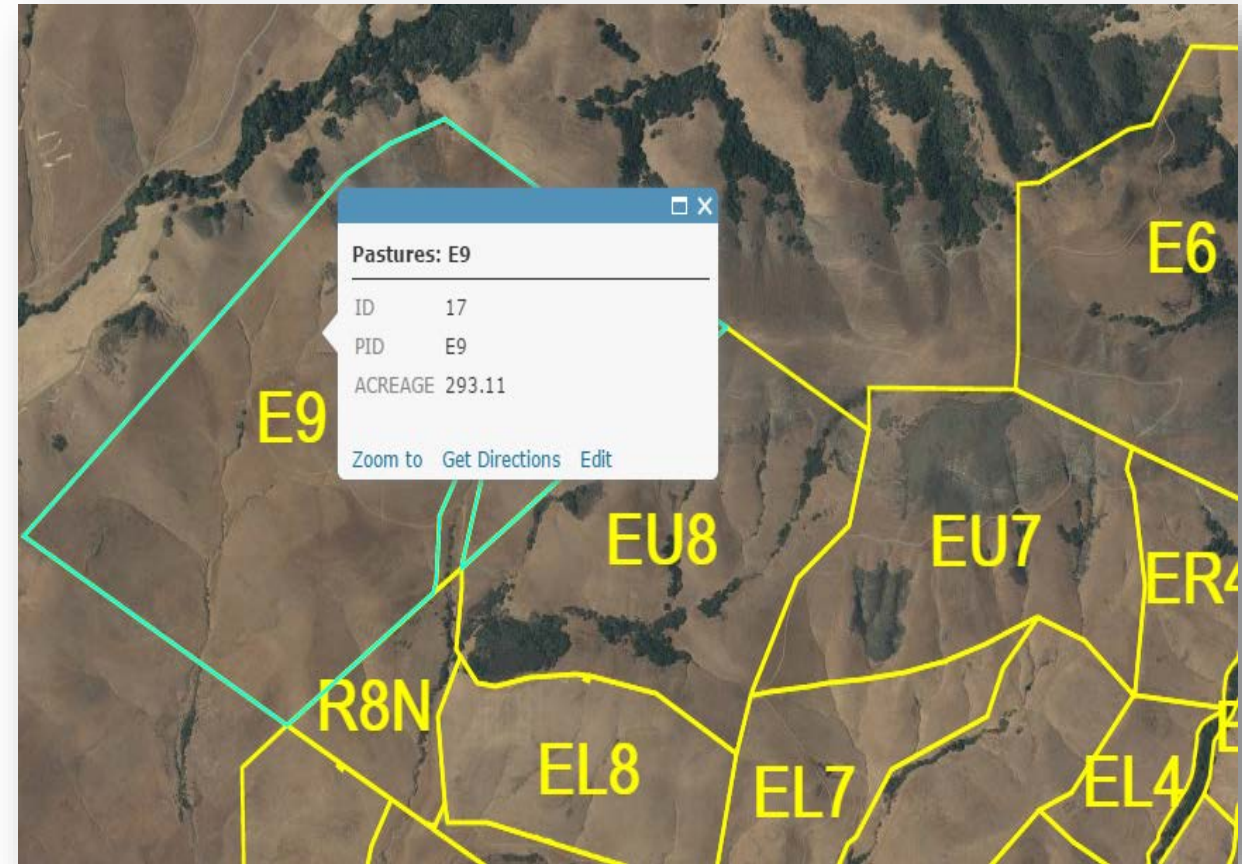
Tiling

- Hexagonal Lattice
- Heuristic approach to minimize nodes



Minimum Number of Nodes Visited

$$293.11 \text{ acres} \times \frac{43,560 \text{ ft}^2}{1 \text{ acre}} \times \frac{\text{area scanned per node}}{384,845 \text{ ft}^2} \approx 33 \text{ nodes}$$



Traveling Salesman Problem

Objective Function

Minimize $\sum c_{ij}x_{ij}$

◦ subject to

- $\sum_i x_{ij} = 1 \forall_i$
- $\sum_j x_{ji} = 1 \forall_j$
- $0 \leq x_{ij} \leq 1$ x_{ij} (integer)
- $u_i - u_j + nx_{ij} \leq n - 1, \forall i, j \in N - \{1\}, i \neq j$

Variables

$$x_{ij} = \begin{cases} 1 & \text{if arc } ij \text{ is in the tour} \\ 0 & \text{otherwise} \end{cases}$$

u: sequence in which node i is visited

n: number of nodes in tour

N: total number of nodes

c: arc length

Pasture E9

Path Length

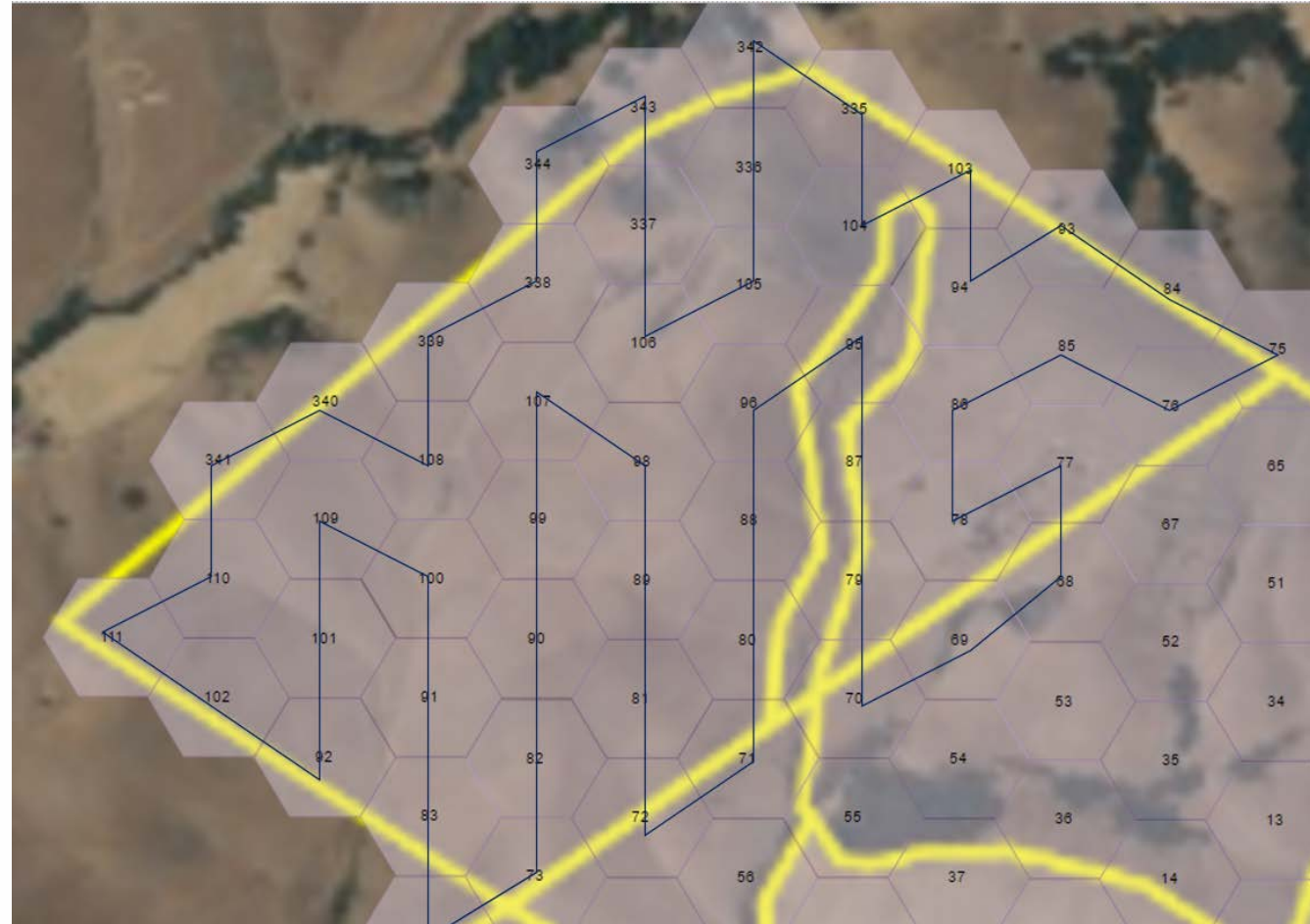
32,129.5ft

Flight Time

$32,129.5\text{ft} \times (52.5\text{ft/s} \times 60\text{s/min})$

+ Ascent /Descent Time

= **10.21 minutes**



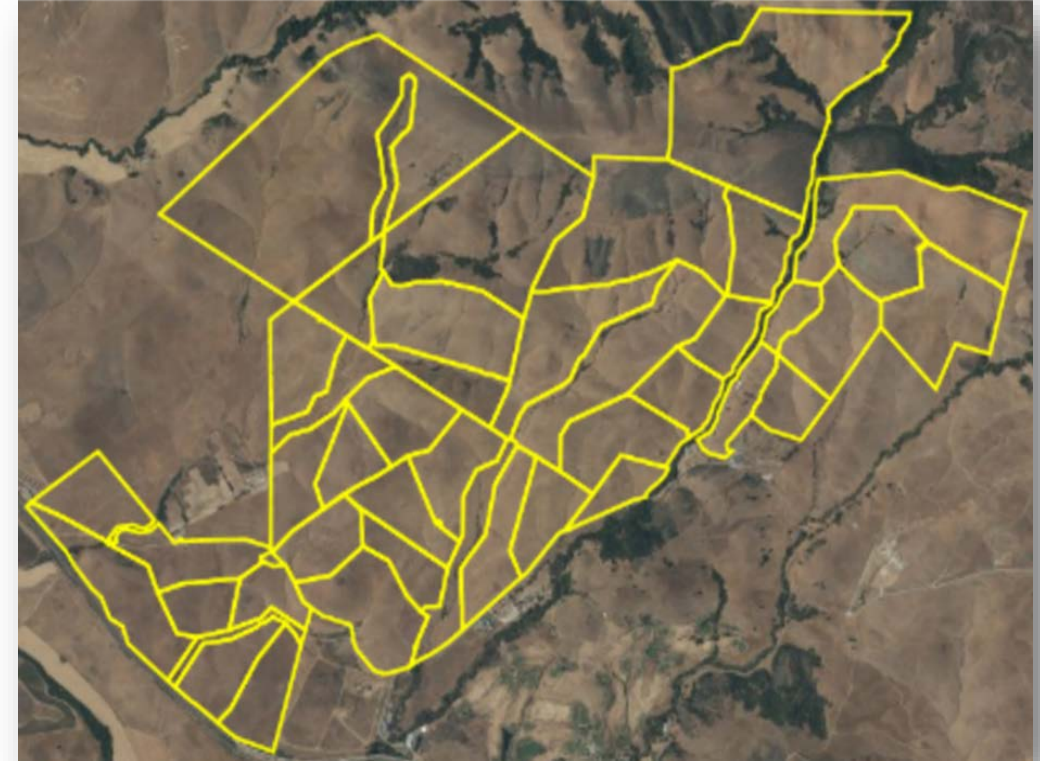
Walters & Escuela Ranches

Minimum Number of Nodes Visited

$$2562 \text{ acres} \times \frac{43,560 \text{ ft}^2}{1 \text{ acre}} \times \frac{\text{area scanned per node}}{384,845 \text{ ft}^2} \approx 290 \text{ nodes}$$

Time to Travel to all Nodes

$$290 \text{ nodes} \times 700 \text{ ft between nodes} \div \frac{52.5 \text{ ft}}{\text{s}} = 64.47 \text{ min}$$

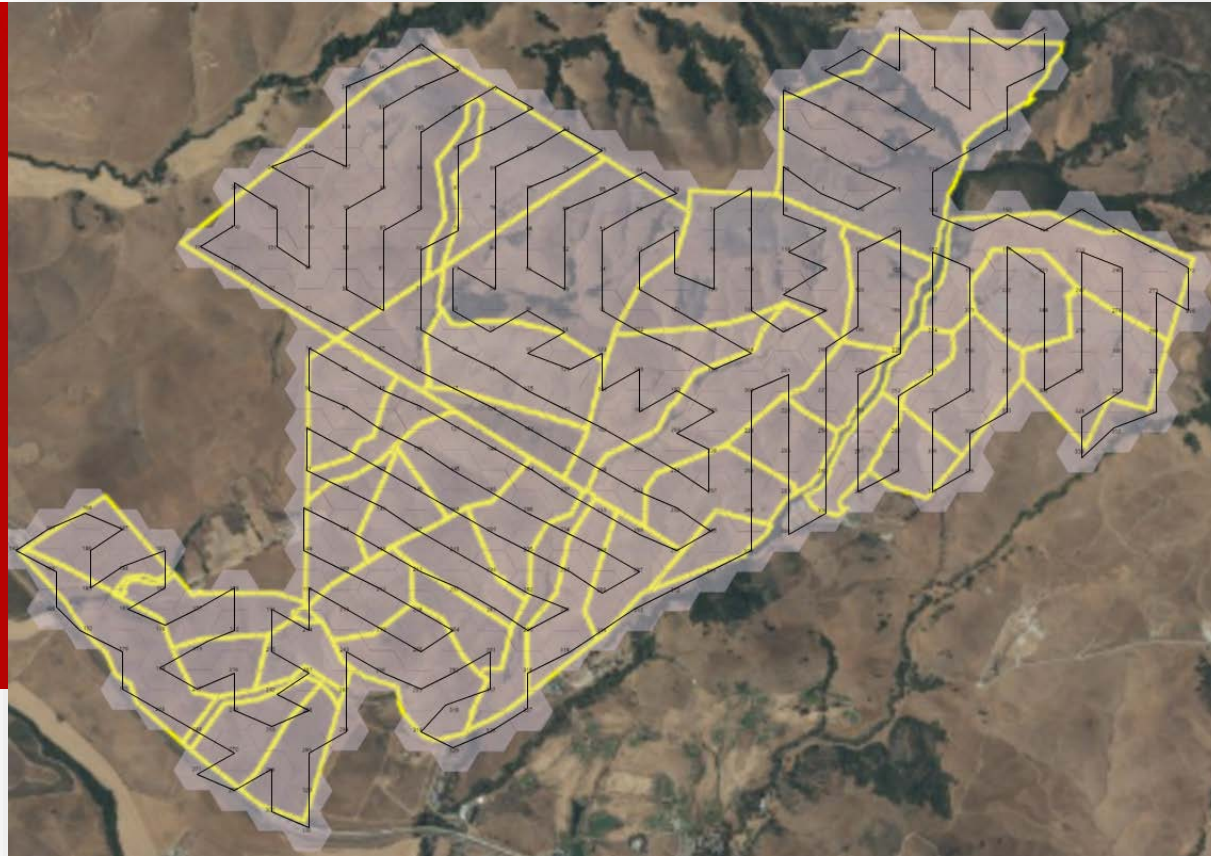


Traditional Grazing

205,508ft

65 min total flight time

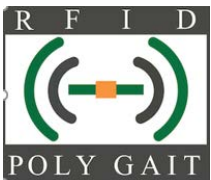
5 Flights



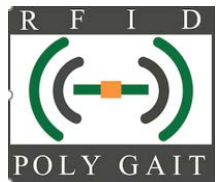
Future @ PolyGAIT

- R&D Goals
 - Leading edge technological innovation and process development, additional industries
 - Hands-on educational methods producing top performing, collaborative, industry leaders
- Collaboration
 - Global & Inclusive
 - Cross-Disciplinary
 - Cross-Profit (Non-Profit w/For Profit)

Thank you!!!



SEPTEMBER 30 - OCTOBER 1, 2020



RFID
JOURNAL
VIRTUALLY
LIVE!

SEPTEMBER 30 - OCTOBER 1, 2020

THANK YOU

RFID
JOURNAL
VIRTUALLY
LIVE!